

Autodesk Inventor

Engineer s Handbook

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Joints / Fixed Joints

Clamping Joint Calculator

[قابل توجه خوانندگان عزیز: کلیه مطالب

این هندبوک از سایت شرکت Autodesk

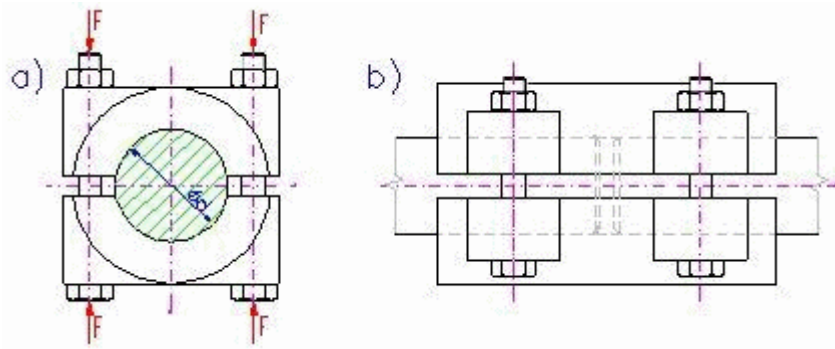
کپی برداری شده است.]

Separated hub joints

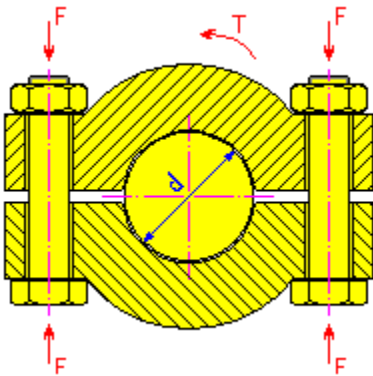
Fit with smaller interference H8/n7, H8/p7, H7/n6, H7/p6.

Hubs of clamping joints are either separated or slotted.

Clamping joints are suitable for transfer of small and medium torques. You can move and rotate a hub towards the shaft during an assembly. With separated hubs, you can fasten a wheel on a shaft without dismantling the shaft.



Separated hub - formulas for metric calculation



Contact pressure

$$p = \sqrt{\left(\frac{2 \cdot 1000 \cdot k_s \cdot T}{\pi \cdot d^2 \cdot L \cdot v} \right)^2 + \left(\frac{k_s \cdot F_a}{\pi \cdot d \cdot L \cdot v} \right)^2} \quad [\text{MPa}]$$

Minimum hub length

$$l_{\min} = \sqrt{\left(\frac{2 \cdot 1000 \cdot k_s \cdot T}{\pi \cdot d^2 \cdot p_A \cdot v} \right)^2 + \left(\frac{k_s \cdot F_a}{\pi \cdot d \cdot p_A \cdot v} \right)^2} \quad [\text{mm}]$$

Recommended values: $L = (0.6 - 3) d$

Force carried by one bolt

$$F = \frac{F_s}{i} = \frac{p \cdot L \cdot d}{i} \quad [\text{N}]$$

Strength check

$$p \leq p_A$$

where:

F_a axial force [N]

T torque [Nm]

d shaft diameter [mm]

p contact pressure in a joint [MPa]

p_A allowable pressure [MPa]

L hub length [mm]

ν clamping factor $\nu = 0.008$ to 0.1 [-]

k_s slip safety [-]

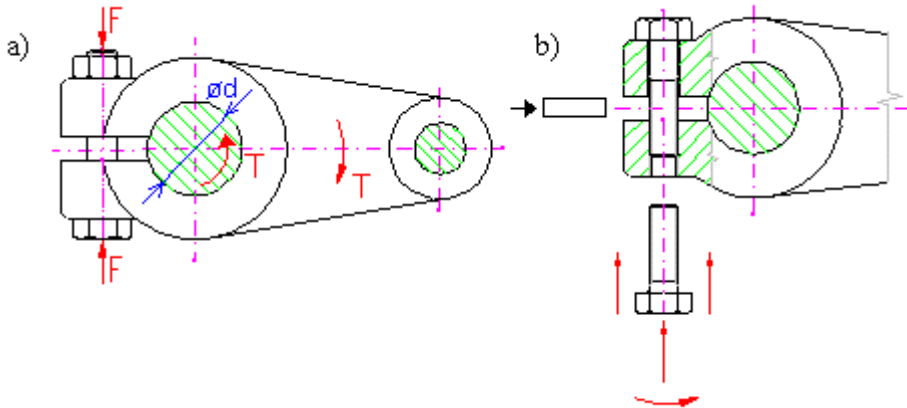
F force carried by one bolt [N]

F_s force carried by all bolts [N]

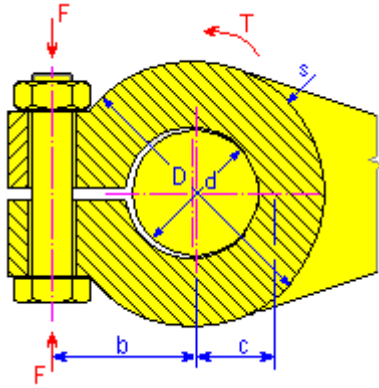
i total number of bolts [-]

Slotted hub joint

Transient fit H8/j7, H8/k7, H7/j6, H7/k6



Slotted hub - formulas for metric calculation



Contact pressure

$$p = \sqrt{\left(\frac{2 \cdot 1000 \cdot k_s \cdot T}{\pi \cdot d^2 \cdot L \cdot v} \right)^2 + \left(\frac{k_s \cdot F_a}{\pi \cdot d \cdot L \cdot v} \right)^2} \quad [\text{MPa}]$$

Minimum hub length

$$l_{\min} = \sqrt{\left(\frac{2 \cdot 1000 \cdot k_s \cdot T}{\pi \cdot d^2 \cdot p_A \cdot v} \right)^2 + \left(\frac{k_s \cdot F_a}{\pi \cdot d \cdot p_A \cdot v} \right)^2} \quad [\text{mm}]$$

Recommended values: $L = (0.6 - 3) d$

Force carried by one bolt

$$F = \frac{p \cdot L \cdot d \cdot c}{i \cdot (c + b)} \quad [\text{N}]$$

Strength check

$$p \leq p_A$$

where:

F_a acting axial force [N]

T torque [Nm]

d shaft diameter [mm]

p contact pressure in a joint [MPa]

p_A allowable pressure [MPa]

L hub length [mm]

ν clamping factor $\nu = 0.008$ to 0.1 [-]

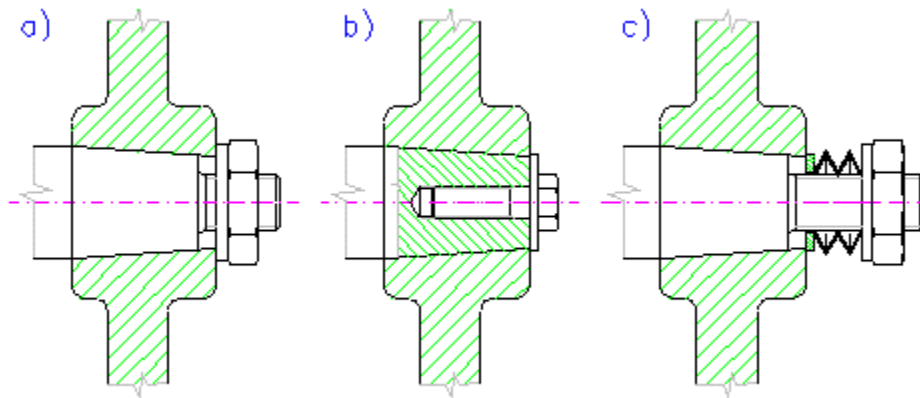
k_s slip safety [-]

F force carried by one bolt [N].

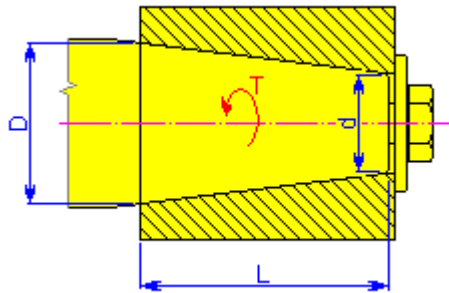
i total number of bolts [-].

Cone joint

In the cone joints, a hub is pressed on the shaft cone end.



Cone joint - formulas for metric calculation



Taper ratio

$$C = 1 : x = \frac{D - d}{L} = 2 \operatorname{tg} \frac{\alpha}{2}$$

Cone gradient

$$\operatorname{tg} \frac{\alpha}{2} = \frac{D - d}{2L}$$

Cone medium diameter

$$d_s = \frac{d + D}{2} \quad [\text{mm}]$$

Required pressure in the joint

$$p = \frac{2 \cdot 1000 \cdot k_s \cdot T \cdot \cos\left(\frac{\alpha}{2}\right)}{\pi \cdot d_s^2 \cdot L \cdot v} \quad [\text{MPa}]$$

Required pressing force

$$F_s = \pi \cdot d_s \cdot L \cdot p \cdot \operatorname{tg}\left(\frac{\alpha}{2} + \varphi\right) = \pi \cdot d_s \cdot L \cdot p \cdot \frac{\operatorname{tg}\left(\frac{\alpha}{2}\right) + v}{1 - \operatorname{tg}\left(\frac{\alpha}{2}\right) \cdot v} \quad [\text{N}]$$

Force for releasing joint

$$F_{S1} = \pi \cdot d_s \cdot L \cdot p \cdot \tan\left(\varphi - \left(\frac{\alpha}{2}\right)\right) = \pi \cdot d_s \cdot L \cdot p \cdot \frac{v - \tan\left(\frac{\alpha}{2}\right)}{1 + v \cdot \tan\left(\frac{\alpha}{2}\right)} \quad [N]$$

Strength check

$$p \leq p_A$$

where:

T torque [Nm]

d small shaft diameter [mm]

D greater shaft diameter [mm]

p contact pressure in a joint [MPa]

p_A allowable pressure [MPa]

L hub length [mm]

v clamping factor v = 0.008 to 0.1 [-]

k_s slip safety [-]

φ friction angle φ = arc tg v

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